

Learning Treatment Effects under Covariate Dependent Left Truncation and Right Censoring

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Left truncation – selection due to delayed entry

- Example: aging studies.
 - ▶ Age is the time scale of interest.
 - ▶ Subjects enrolled at various ages instead of at the time origin (time at birth).

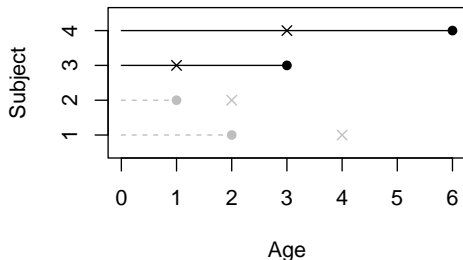
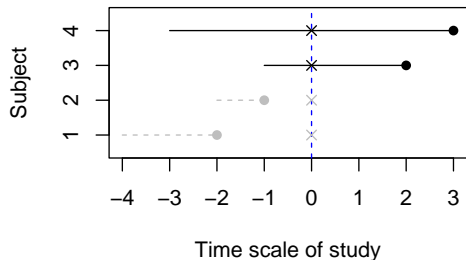


Figure: A toy example for aging study; 'x' - enrollment times; dots - times to events.

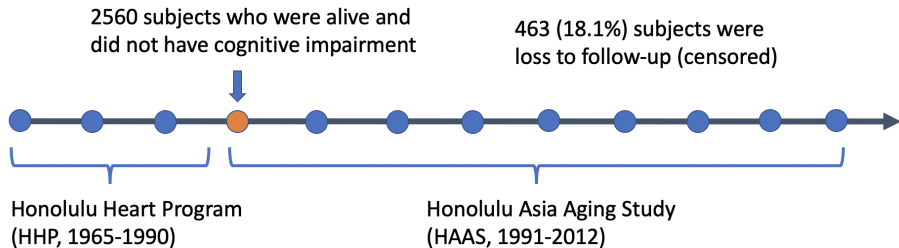
Left truncation – mathematical formulation

- Time-to-event: T^*
- Left truncation time: Q^* – usually the study enrollment time
- T^* is **left truncated** by Q^* if only subjects with $T^* > Q^*$ are included in the data.
- Subjects with early event times tend not to be captured → **selection bias**

Examples:

- Aging studies – age is the time scale of interest
- Pregnancy studies
- Some cancer survivorship studies, e.g., SJLIFE.

HAAS data – Triple biases



- T^* - age to moderate cognitive impairment or death
 Q^* - age at entry of HAAS
Only subjects with $T^* > Q^*$ are included.
- **Triple biases:**
 - **Selection bias from left truncation** – early event times are underrepresented.
 - Confounding in observational data.
 - Informative right censoring.

First focus on handling left truncation

Literature for handling left truncation

Under random left truncation / quasi-independence assumption

- Likelihood-based approaches.

! Strong assumption – may be violated in practice.

e.g., In HAAS data,

conditional Kendall's tau test for quasi-independence (Tsai, 1990): $p\text{-value} = 0.0014$.

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Under covariate dependent left truncation

- In regression settings: Cox model with risk set adjustment.

- For marginal survival probability: inverse probability weighting (IPW) (Vakulenko-Lagun et al., 2022).

! Sensitive to misspecification of the truncation model; inefficient.

Our contributions

- Derive the efficient influence curve (EIC) for the expectation of a transformed event time.
- Construct EIC-based estimators that are shown to have favorable properties.
 - ▶ Model double robustness
 - ▶ Rate double robustness
 - ▶ Semiparametric efficiency
- Provide technical conditions for the asymptotic properties that appear to not have been carefully examined in the literature for time-to-event data.
- Our work represents the **first attempt** to construct doubly robust estimators in the presence of left truncation.
 - ▶ Does NOT fall under the established framework of coarsened data where doubly robust approaches were developed.

Notation and estimand

- Q - left truncation time; T - event time; Z - covariates
- Variables with '*' – full data, i.e., if there were no left truncation;
- Variables without '*' – observed data: only contains subjects with $Q^* < T^*$.
 $O = (Q, T, Z)$.

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 $O = (Q, T, Z)$.

- Estimand: $\theta := \mathbb{E}\{\nu(T^*)\}$, where ν is a given function.
 - ▶ e.g., $\nu(t) = \mathbb{1}(t > t_0) \implies \theta = \mathbb{P}(T^* > t_0)$ (survival probability).
 - ▶ e.g., $\nu(t) = \min(t, t_0) \implies \theta = \mathbb{E}\{\min(T^*, t_0)\}$ (restricted mean survival time, RMST).

Assumptions

① **Conditional quasi-independence:**

Q^* and T^* are conditionally independent given Z^* on the observed region $\{t > q\}$.
- The dependence of Q^* and T^* can be explained by measured covariates.

② **Positivity:** $\mathbb{P}(Q^* < T^* \mid T^*, Z^*) > 0$ a.s..

③ **Overlap:** There exist $0 < \tau_1 < \tau_2 < \infty$ and constants $\delta_1, \delta_2 > 0$ such that $T \geq \tau_1$ a.s. and $Q \leq \tau_2$ a.s. in the full data; $1 - F(\tau_2|Z) \geq \delta_1$ a.s., and $G(\tau_1|Z) \geq \delta_2$ a.s..

Efficient influence curve and double robustness

- Efficient influence curve: $\varphi(O) =$ a constant factor times

$$U(\theta; F, G) = \underbrace{\frac{\nu(T) - \theta}{G(T|Z)}}_{\text{IPW}} - \underbrace{\int_0^\infty m_\nu(v, Z; F) \cdot \frac{F(v|Z)}{1 - F(v|Z)} \cdot \frac{d\bar{M}_Q(v; G)}{G(v|Z)}}_{\text{Augmentation}}$$

- F : the conditional CDF of $T^* | Z^*$.

- G : the conditional CDF of $Q^* | Z^*$.

(both can be nonparametrically identified from the observed data distribution)

- $m_\nu(v, z; F) = \mathbb{E}_F\{\nu(T^*) - \theta \mid T^* < v, Z^* = z\}$.

- The semiparametric efficiency bound : $\mathbb{E}(\varphi^2)$.

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- The semiparametric efficiency bound : $\mathbb{E}(\varphi^2)$.

Double robustness:

$\mathbb{E}\{U(\theta_0; F, G)\} = 0$ if either $F = F_0$ or $G = G_0$.

Estimation: model double robustness under asymptotic linearity

Let $\{O_i\}_{i=1}^n$ be an observed random sample of size n ; $O_i = (Q_i, T_i, Z_i)$.

- First estimate F and G
- Then solve $\sum_{i=1}^n U_i(\theta; \hat{F}, \hat{G}) = 0$ for $\theta \implies \hat{\theta}_{dr}$

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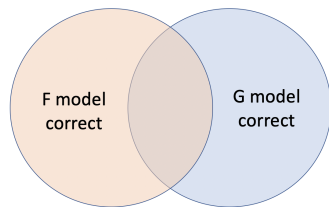
- First estimate F and G
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When (semi-)parametric models are used,

- $\hat{\theta}_{dr}$ is CAN if **either** the model for F or G is correctly specified.

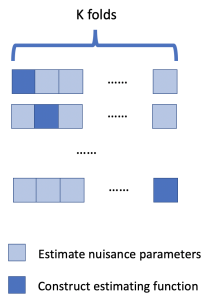
Furthermore, when both models are correctly specified,

- $\hat{\theta}_{dr}$ achieves the semiparametric efficiency bound;
- Consistent estimator for the asymptotic variance.



Estimation: Rate double robustness with cross-fitting

K -fold cross-fitting



$$\implies \hat{\theta}_{cf}$$

Estimation: Rate double robustness with cross-fitting

Suppose

- the nuisance estimators are uniformly consistent;
- the integral product rate $\mathcal{D}(\hat{F}, \hat{G}; F_0, G_0) = o_p(n^{-1/2})$.

$$\mathcal{D}(F, G; F_0, G_0) := \mathbb{E} \left[\left| \int_{\tau_1}^{\tau_2} \{a(t, \mathbf{Z}; F) - a(t, \mathbf{Z}; F_0)\} \cdot \mathbb{1}(Q \leq t < T) \cdot d \left\{ \frac{1}{G(t|\mathbf{Z})} - \frac{1}{G_0(t|\mathbf{Z})} \right\} \right|^2 \right],$$

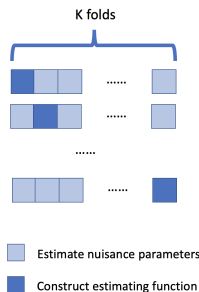
$$a(t, \mathbf{Z}; F) = \int_0^t \{\nu(u) - \theta\} dF(u|\mathbf{Z}) / \{1 - F(t|\mathbf{Z})\}.$$

Then

- $\hat{\theta}_{cf}$ is CAN; achieves the semiparametric efficiency bound;
- Consistent estimator for the asymptotic variance.

Nonparametric methods can be used to estimate F and G !

K-fold cross-fitting



$$\implies \hat{\theta}_{cf}$$

Literature for treatment effect estimation

For handling confounding bias

- Average treatment effect (ATE) ← Augmented IPTW (AIPTW)
- Conditional average treatment effect (CATE) ← Orthogonal learners (Foster and Syrgkanis, 2023)
 - ▶ e.g., R-learner (Nie and Wager, 2021); DR-learner (Kennedy, 2023).

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For right censored time-to-event data: confounding + censoring bias

- Doubly robust estimators for ATE (Zhang and Schaubel, 2012 ; Bai et al., 2017; Sjolander and Vansteelandt, 2017; Westling et al., 2023; Luo et al., 2023)
- Orthogonal learners for CATE (Morzywolek et al., 2023; Xu et al., 2024)

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- Orthogonal learners for CATE (Morzywolek et al., 2023; Xu et al., 2024)

For handling all three biases

- Methods based on regression models (Cheng and Wang, 2012; Cheng and Wang, 2015).
- IPW-based approaches
- ! Sensitive to model misspecifications; inefficient.

Our contributions

- Develop a general doubly robust framework for handling covariate dependent left truncation and right censoring.
- Construct model doubly robust and rate doubly robust estimators for ATE.
- Construct orthogonal and doubly robust learners for CATE that are shown to achieve oracle rate.
- Our work represents the **first attempt** to
 - ▶ develop doubly robust approaches that address all three sources of biases;
 - ▶ investigate CATE estimation for left truncated and right censored data.

Notation

- Q : left truncation time; T : event time; Z : covariates.
- C : censoring time; $D = C - Q$: residual censoring time;
- A : binary treatment assignment.

- Variables with '*' – truncation-free data; without '*' – truncated data.
- $T^*(a)$ – potential event time under treatment a .

- Observe $O = (Q, X, \Delta, A, Z)$ only if $Q^* < T^*$.
- $X = \min(T, C)$, $\Delta = I(T < C)$.

Assumptions

- ① No unmeasured confounding, consistency.
- ② Conditional independent truncation: $Q^* \perp\!\!\!\perp T^* \mid A^*, Z^*$.
- ③ Conditional noninformative residual censoring: $D \perp\!\!\!\perp (T - Q) \mid Q, A, Z$.
- ④ Positivity.
- ⑤ Overlap.

Doubly robust operator for left truncation

- $\zeta(T^*, A^*, Z^*; \theta)$ – an unbiased and non-degenerate estimating function for θ .
- The EIC for θ in truncated data: a constant factor times

$$\underbrace{\frac{\zeta(T, A, Z; \theta)}{G(T|A, Z)}}_{\text{IPW}} - \underbrace{\int_0^\infty m_\zeta(v, A, Z; \theta, F) \cdot \frac{F(v|A, Z)}{1 - F(v|A, Z)} \cdot \frac{d\bar{M}_Q(v; G)}{G(v|A, Z)}}_{\text{Augmentation}}$$

- F : the conditional CDF of $T^* | A^*, Z^*$.
- G : the conditional CDF of $Q^* | A^*, Z^*$.
- $m_\zeta(v, a, z; \theta, F) = \mathbb{E}\{\zeta(T^*, A^*, Z^*; \theta) | T^* \leq v, A^* = a, Z^* = z\}$.

- **truncAIPW**: generalize to any function ζ

Doubly robust operator for censoring

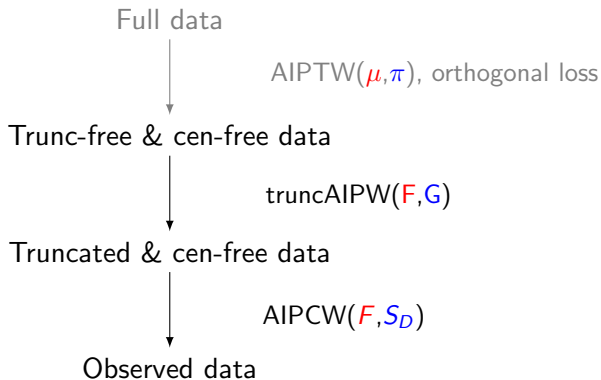
- Adapt the **AIPCW** (Rotnitzky and Robins, 2005) to the **residual time scale**.
- For any function $\xi(Q, T, A, Z)$ in censoring-free data,

$$\underbrace{\frac{\Delta \xi(Q, X, A, Z)}{S_D(X - Q | Q, A, Z)}}_{\text{IPCW}} + \underbrace{\int_0^\infty \mathbb{E}_F \{ \xi(Q, T, A, Z) | T - Q \geq u, Q, A, Z \} \cdot \frac{dM_D(u; S_D)}{S_D(u | Q, A, Z)}}_{\text{Augmentation}}$$

- Recall $D = C - Q$: the residual censoring time.
- S_D : the conditional survival function of $D | Q, A, Z$.
- Recall F : the conditional CDF of $T^* | A^*, Z^*$.

General framework and double robustness

- **General framework:**



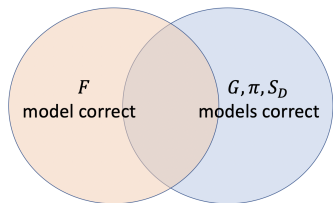
- **Double robustness:** The expectation is maintained (up to a constant factor) if either F or (G, S_D) is the truth.

ATE estimation

- Estimand: $\theta_a = \mathbb{E}[\nu\{T^*(a)\}]$. Propensity score: $\pi(z) = \mathbb{P}(A^* = 1|Z^* = z)$.
- AIPTW estimating function $\xrightarrow{\text{truncAIPW, AIPCW}}$ $U_a(\theta_a; F, G, \pi, S_D)$
- **Double robustness:** $\mathbb{E}\{U_a(\theta_a; F, G, \pi, S_D)\} = 0$ if either F or (G, π, S_D) is the truth.

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- **Double robustness:** $\mathbb{E}\{U_a(\theta_a; F, G, \pi, S_D)\} = 0$ if either **F** or (G, π, S_D) is the truth.
- Estimation:
Model double robustness. Rate double robustness.



- Require the **product error rate** between \hat{F} and $(\hat{G}, \hat{\pi}, \hat{S}_D)$ to be faster than $n^{-1/2}$.

CATE estimation

- Estimand: $\tau(z) = \mathbb{E}[\nu\{T^*(1)\} - \nu\{T^*(0)\} \mid Z^* = z]$.
- Loss function $\ell(T^*, A^*, Z^*; \tau, F, \pi) \xrightarrow{\text{truncAIPW, AIPCW}} \tilde{\ell}(O; \tau, F, G, \pi, S_D)$
 - ▶ R-loss \rightarrow ltrcR-loss
 - ▶ DR-loss \rightarrow ltrcDR-loss
- **Neyman orthogonality** and **double robustness** are maintained.

CATE estimation

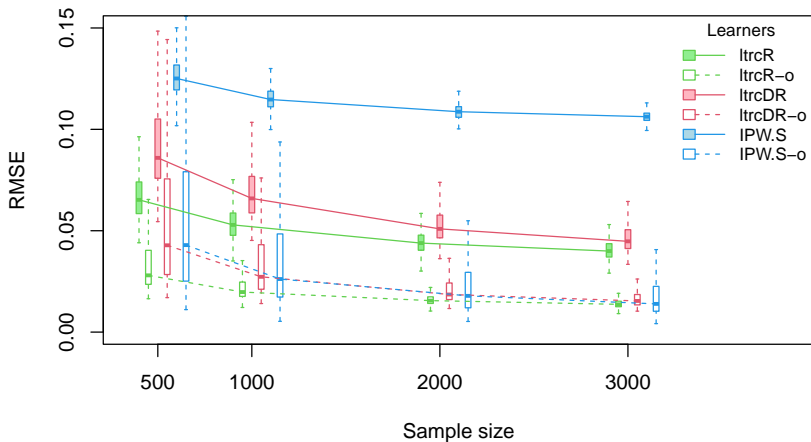
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 - ▶ DR-loss \rightarrow ltrcDR-loss
- **Neyman orthogonality** and **double robustness** are maintained.
- $\hat{\tau} \leftarrow K$ -fold cross-fitted empirical risk minimization.
- Estimation errors of the nuisance parameter only have **higher order impact** on $\hat{\tau} - \tau_0$.
 - ▶ If the nuisance are estimated at faster than $n^{-1/4}$ rate
 $\rightarrow \hat{\tau}$ achieve **oracle rate**, i.e., estimation error rate if the nuisance were known.

Simulation - CATE

- 500 simulated data sets. Estimand: $\tau(z) = \mathbb{E}\{\log T^*(1) - \log T^*(0) \mid Z^* = z\}$.
- Truncation rate: 31.3%; treatment rate: 50%; censoring rate 48.4%. $RMSE^2 = \frac{1}{n} \sum_{i=1}^n \{\hat{\tau}(V_i) - \tau_0(V_i)\}^2$.



Summary:

- We have developed a general doubly robust framework for handling covariate dependent left truncation and right censoring.
 - ▶ e.g., estimate ATE, CATE.
 - ▶ Can also be applied to estimate parameters in marginal structure models.

Acknowledgment:

- We thank Dr. Kendrick Li on the helpful discussion on EIC derivation.

References and contact info:

- **Wang, Y.**, Ying, A. and Xu, R. (2024). Doubly robust estimation under covariate-induced dependent left truncation. *Biometrika* 111: 789–808.
- **Wang, Y.**, Ying, A. and Xu, R. (2024+). Learning treatment effects under covariate dependent left truncation and right censoring. (*Work in progress*).
- R-package: `truncAIPW`. Email: yuw079@ucsd.edu

I'm on the job market for positions starting 2025 Fall!

Appendix

Assumptions

f, g, h : the densities of $T^*|Z^*$, $Q^*|Z^*$ and Z^* , respectively.

- **Conditional quasi-independence:** The observed data density for (Q, T, Z) satisfies

$$p_{Q,T,Z}(q, t, z) = \begin{cases} f(t|z)g(q|z)h(z)/\beta, & \text{if } t > q, \\ 0, & \text{otherwise,} \end{cases}$$

where $\beta = \mathbb{P}(Q^* < T^*) = \int \mathbb{1}(q < t)f(t|z)g(q|z)h(z) dt dq dz$.

- **Positivity:** $G(T^*|Z^*) > 0$ a.s.
- **Overlap:** There exists $0 < \tau_1 < \tau_2 < \infty$ such that $T^* \geq \tau_1$ a.s., $Q^* \leq \tau_2$ a.s.; also $G(\tau_1|Z^*) \geq \delta_1$ a.s. and $F(\tau_2|Z^*) \leq 1 - \delta_2$ a.s. for some constants $\delta_1 > 0$ and $\delta_2 > 0$.